

# P & NP

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- A decision problem is in the P class, if there exists an algorithm for solving it, whose **worst case** running time is bounded by  $p(|x|)$ .

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  - **Angelic choice**: if at least one execution trajectory yields “yes,” then the answer is “yes.”
  - One can implement **non-deterministic guess** (say, guess the satisfying assignment for a 3-CNF or guess a Hamiltonian cycle in a graph).

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  - Examples of  $y$ : the satisfying assignment; the Hamiltonian cycle; ...

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- Equivalence of definitions:



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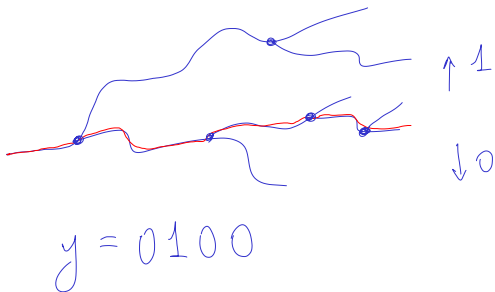
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- Informally, NP-complete problems are the **hardest possible** problems in NP.
  - In particular, if an NP-complete problem is solvable in poly time, then  $P = NP$ .
  - Contraposition: if  $P \neq NP$  (which is highly likely), then any NP-complete problem is not in P.

# NP-Completeness

- **m-reduction** (Carp reduction):  $A$  is reducible to  $B$  ( $A \leq_m^P B$ ), if there exists a polytime computable function  $f: \Sigma^* \rightarrow \Sigma^*$ , such that  $A(x) = 1 \iff B(f(x)) = 1$ .

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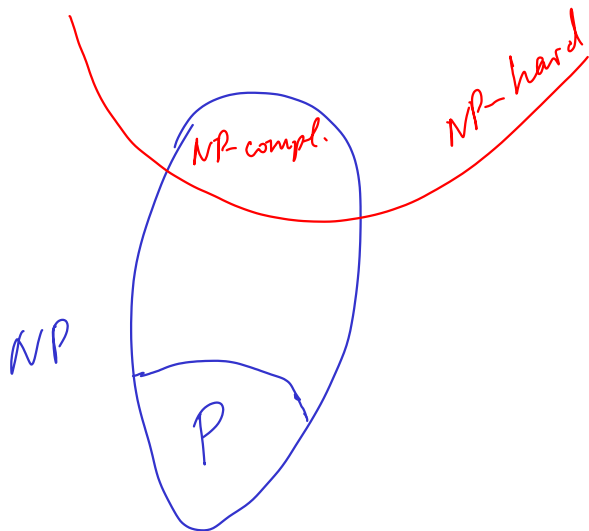
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- A problem  $B$  is **NP-hard** if  $A \leq_m^P B$  for any  $A \in \text{NP}$ .
- $B$  is **NP-complete** if  $B \in \text{NP}$  and  $B$  is NP-hard.

# Complexity Picture

(if  $P \neq NP$ )



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  - Suppose we know  $A$  to be already NP-hard.
  - In order to prove NP-hardness of a problem  $B$ , we reduce the **old** problem  $A$  to  $B$ .
- But how to bootstrap and obtain the first example of an NP-complete problem?

# Cook – Levin Theorem

## Theorem

*SAT (satisfiability of arbitrary Boolean formulae) NP-complete.*

## Example: Graph Coloring

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- The problem is **3-colorability of graphs**.
- Let us first recall what a graph is.

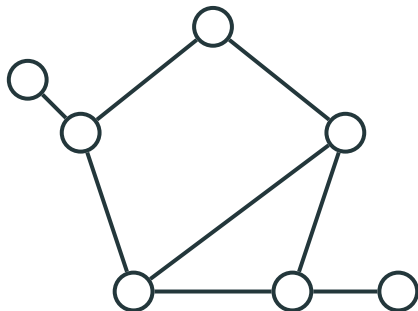
# Graphs

An **undirected graph** is a formed by set of *vertices*, some of which are connected by *edges*.



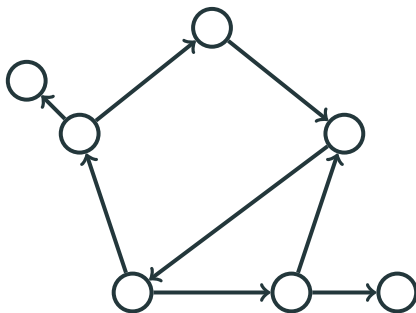
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# Graphs

In a **directed** graph, edges have arrows on them:



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- *Parallel edges*: two vertices connected by more than one edge.



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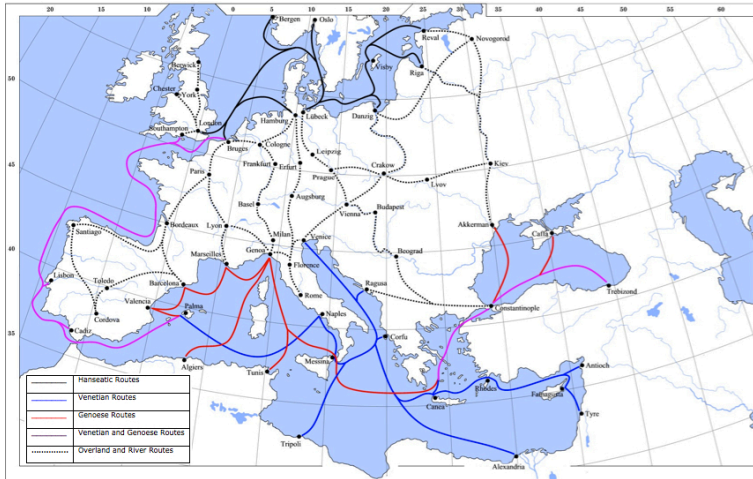
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- Note that in a directed graph edges connecting two vertices in different directions are **not** considered parallel.



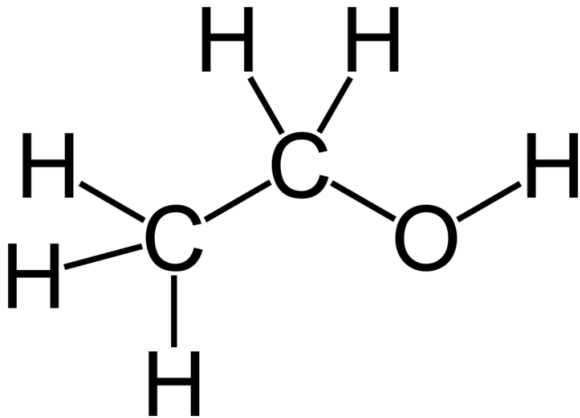
# Applications of Graphs

Maps (GIS): vertices = cities, edges = routes.



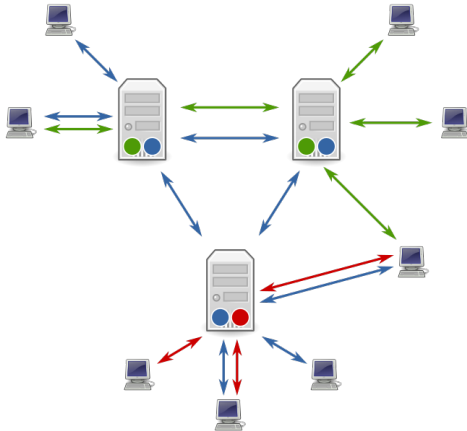
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Chemistry: graphs of molecular structure.



# Applications of Graphs

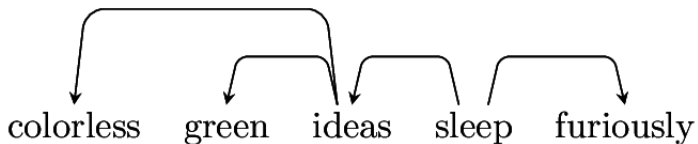
Internet: network topology.



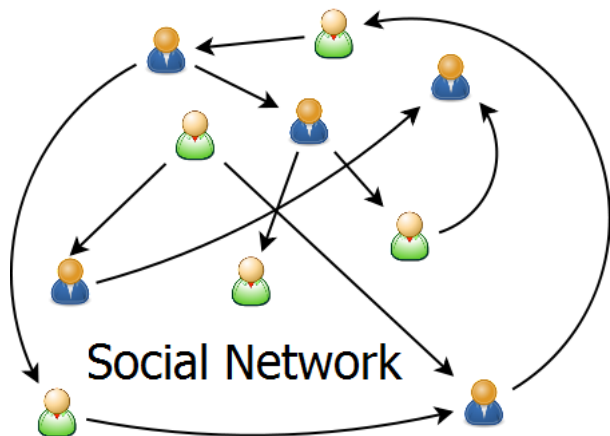
Benjamin D. Esham @ Wikipedia

# Applications of Graphs

Linguistics: syntactic dependencies.



# Applications of Graphs



Zigomitos Athanasios - Thor4bp @ Wikipedia

## Graph: Formal Definition

- A pseudograph can be formally defined as  $G = (V, E)$ , where  $V$  is the set of vertices (arbitrary finite set) and  $E \subseteq V \times V = \{(u, v) \mid u, v \in V\}$  is the set of edges, such that  $(u, v) \in E \iff (v, u) \in E$ .

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  - A directed graph is an arbitrary irreflexive relation.
  - The formal definition of multigraph is more involved.

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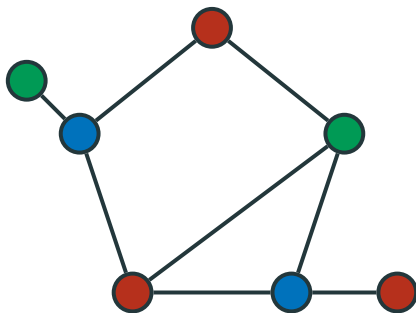
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- Example: 3-coloring  $c: V \rightarrow \{\mathbf{R}, \mathbf{G}, \mathbf{B}\}$ .

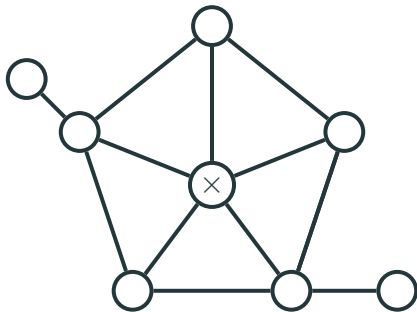
# 3-Coloring

For example, this graph is 3-colorable:



# 3-Coloring

... and this one is not:





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- The 3-colorability problem (given a graph  $G$ , answer whether it is 3-colorable) clearly belongs to the NP class.
- Indeed, we can non-deterministically guess the coloring (“hint”) and then check its correctness in poly time.
- Thus, a particular case of Cook – Levin theorem states that  $3\text{-COLOR} \leq_m^P \text{SAT}$ .

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- For any graph  $G$  we can construct a Boolean formula  $\varphi_G$ , which is satisfiable if and only if  $G$  is 3-colorable.

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- Moreover, each correct 3-coloring of  $G$  will correspond to a satisfying assignment of  $\varphi_G$ , and vice versa.

# Reducing 3-COLOR to SAT

- For each vertex  $v_i \in V$ , introduce the following Boolean variables:

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- $\varphi_G$  will represent natural conditions on these propositions.



# Reducing 3-COLOR to SAT

$$\begin{aligned}\varphi_G = & \bigwedge_{v_i \in V} ((r_i \vee g_i \vee b_i) \wedge \\ & (\neg r_i \vee \neg g_i) \wedge (\neg r_i \vee \neg b_i) \wedge (\neg b_i \vee \neg g_i)) \wedge \\ & \bigwedge_{(v_i, v_k) \in E} ((\neg r_i \vee \neg r_k) \wedge (\neg g_i \vee \neg g_k) \wedge (\neg b_i \vee \neg b_k))\end{aligned}$$

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- By the way,  $\varphi_G$  is a 3-CNF.

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- Thus, if SAT were solvable in poly time, so would have been 3-COLOR.
- In reality, however, we **do not know** a polynomial algorithm for SAT, and such reductions give some evidence **against** its existence.
- The idea of Cook – Levin theorem is that **any** NP guessing can be represented as guessing a satisfying assignment for a Boolean formula.

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- While there is no known polynomial algorithm for SAT, modern **SAT solvers** are quite efficient in practice.
  - One of the reasons is that we measure **worst case** complexity, and instances which appear in practice could avoid such cases.
- Cook – Levin style reductions allow to use SAT solvers for other NP problems.

# Cook – Levin Theorem

## Theorem

*SAT is NP-complete, that is, if  $A \in NP$ , then  $A$  is  $m$ -reducible to SAT.*

# Turing Machines

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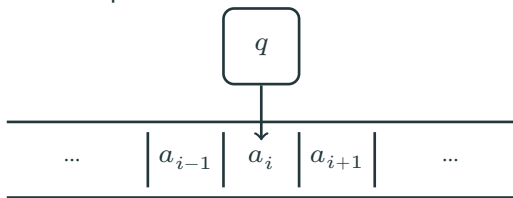
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- Let us define one such model, namely, **Turing machines**.

# Turing Machines

- A Turing machine is a tuple  $\mathfrak{M} = \langle \Sigma, \Gamma, Q, q_0, q_F, \Delta \rangle$ , where:
  - $\Sigma$  is the *external alphabet* (in which input and output are formulated);
  - $\Gamma \supseteq \Sigma$  is the *internal alphabet* (used in the computation process);
  - $Q$  is a finite set of *states*;
  - $q_0$  is the starting state and  $q_F$  is the final one;
  - $\Delta$  is the set of *rules* (also finite).

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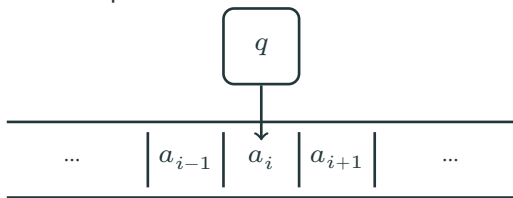
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- At each moment, only a finite part of the tape is populated by meaningful symbols; the rest is padded by “blank” symbols  $B \in \Gamma - \Sigma$ .

# Turing Machines

- **Rules** of  $\mathfrak{M}$  (elements of  $\Delta$ ) are of the form  $\langle p, a \rangle \rightarrow \langle q, b, d \rangle$ , where  $p, q \in Q$ ,  $a, b \in \Gamma$ , and  $d \in \{L, R, N\}$ .

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- Such a rule is executed as follows. If  $\mathfrak{M}$  keeps  $p$  in its internal memory and observes  $a$  on the tape, then the following move is performed:
  1. replace  $a$  with  $b$  in the cell;
  2. replace  $p$  with  $q$  in the internal memory;
  3. if  $d = L$ , move one cell left; if  $d = R$ , move one cell right; if  $d = N$ , stay on the same cell.

# Turing Machines

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- Once a machine runs into state  $q_F$ , it stops successfully, and the word on the tape is the output.
- It is also possible to stop unsuccessfully or to run infinitely long.

## NP and co-NP

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- This class is called co-NP.
- Example: SAT is in NP, while TAUT (checking whether a Boolean formula is a tautology) is in co-NP.

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- Moreover, if the computation is polynomial, it can be performed also polynomially on the Turing machine.
  - The degree of the polynomial could change.

# Cook – Levin Theorem

## Theorem

*SAT is NP-complete, that is, if  $A \in NP$ , then  $A$  is  $m$ -reducible to SAT.*