# NP-Completeness Cook – Levin Theorem

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- The size of input, |x| is the length of x in symbols.
- A decision problem is in the P class, if there exists an algorithm for solving it, whose **worst case** running time is bounded by p(|x|).

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  - Angelic choice: if at least one execution trajectory yields "yes," then the answer is "yes."
  - One can implement non-deterministic guess (say, guess the satisfying assignment for a 3-CNF or guess a Hamiltonian cycle in a graph).

• **m-reduction** (Carp reduction): *A* is reducible to B ( $A \leq_m^P B$ ), if there exists a polytime computable function  $f \colon \Sigma^* \to \Sigma^*$ , such that  $\overline{A(x) = 1} \iff B(f(x)) = 1$ .

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- A problem B is **NP-hard** if  $A \leq_m^P B$  for any  $A \in NP$ .
- *B* is **NP-complete** if  $B \in NP$  and *B* is NP-hard.

## Cook – Levin Theorem

#### Theorem

SAT (satisfiability of arbitrary Boolean formulae) NP-complete, that is, if  $A \in NP$ , then A is m-reducible to SAT.

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- The problem is **3-colorability of graphs.**

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• We color vertices into colors of a set *C*, and our coloring is correct, if each edge connects vertices of different colors.

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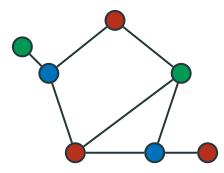
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- Example: 3-coloring  $c \colon V \to \{\mathbf{R}, \mathbf{G}, \mathbf{B}\}.$

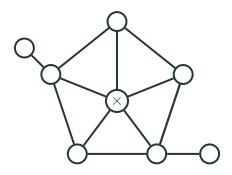


#### For example, this graph is 3-colorable:





... and this one is not:



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- The 3-colorability problem (given a graph *G*, answer whether it is 3-colorable) clearly belongs to the NP class.
- Indeed, we can non-deterministically guess the coloring ("hint") and then check its correctness in poly time.
- Thus, a particular case of Cook Levin theorem states that 3-COLOR  $\leq_m^P$  SAT.

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- The reducing function  $f\colon G\mapsto \varphi_G$  will be poly-time computable.
- Moreover, each correct 3-coloring of G will correspond to a satisfying assignment of  $\varphi_G$ , and vice versa.

- For each vertex  $v_i \in V$ , introduce the following Boolean variables:
  - $r_i$  " $v_i$  is colored red"
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- $\varphi_G$  will represent natural conditions on these propositions.

$$\begin{split} \varphi_G &= \bigwedge_{v_i \in V} \bigl( (\mathbf{r}_i \vee g_i \vee b_i) \wedge \\ (\neg \mathbf{r}_i \vee \neg g_i) \wedge (\neg \mathbf{r}_i \vee \neg b_i) \wedge (\neg b_i \vee \neg g_i) \bigr) \wedge \\ &\bigwedge_{(v_i, v_k) \in E} \bigl( (\neg \mathbf{r}_i \vee \neg \mathbf{r}_k) \wedge (\neg g_i \vee \neg g_k) \wedge (\neg b_i \vee \neg b_k) \bigr) \end{split}$$

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• 3-colorings of G and satisfying assignments of  $\varphi_G$  are in one-to-one correspondence.

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- 3-colorings of G and satisfying assignments of  $\varphi_G$  are in one-to-one correspondence.
- By the way,  $\varphi_G$  is a 3-CNF.

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- Thus, if SAT were solvable in poly time, so would have been 3-COLOR.
- In reality, however, we **do not know** a polynomial algorithm for SAT, and such reductions give some evidence **against** its existence.
- The idea of Cook Levin theorem is that any NP guessing can be represented as guessing a satisfying assignment for a Boolean formula.

#### Theorem

SAT is NP-complete, that is, if  $A \in NP$ , then A is m-reducible to SAT.

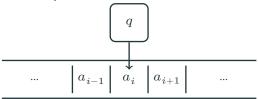
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- This requires a formal notion of what an algorithm is, that is, a formal **model of computation.**

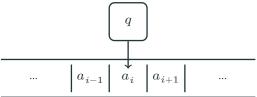
- In order to prove Cook Levin theorem, we need to show that  $A \leq_m^P$  SAT for **any**  $A \in NP$ .
- This requires a formal notion of what an algorithm is, that is, a formal **model of computation.**
- Let us define one such model, namely, **Turing machines.**

- A Turing machine is a tuple  $\mathfrak{M} = \langle \Sigma, \Gamma, Q, q_0, q_F, \Delta \rangle$ , where:
  - $\Sigma$  is the *external alphabet* (in which input and output are formulated);
  - $\Gamma \supseteq \Sigma$  is the *internal alphabet* (used in the computation process);
  - $\cdot Q$  is a finite set of *states*;
  - $\cdot \, q_0$  is the starting state and  $q_F$  is the final one;
  - $\cdot \ \Delta$  is the set of *rules* (also finite).

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• At each moment, only a finite part of the tape is populated by meaningful symbols; the rest is padded by "blank" symbols  $B \in \Gamma - \Sigma$ .

• **Rules** of  $\mathfrak{M}$  (elements of  $\Delta$ ) are of the form  $\langle p, a \rangle \rightarrow \langle q, b, d \rangle$ , where  $p, q \in Q$ ,  $a, b \in \Gamma$ , and  $d \in \{L, R, N\}$ .

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- Such a rule is executed as follows. If  $\mathfrak{M}$  keeps p in its internal memory and observes a on the tape, then the following move is performed:
  - 1. replace a with b in the cell;
  - 2. replace p with q in the internal memory;
  - 3. if d = L, move one cell left; if d = R, move one cell right; if d = N, stay on the same cell.

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- A deterministic machine, on a given input, has a unique execution trajectory; in general, the trajectory may branch.
- Once a machine runs into state  $q_F$ , it stops successfully, and the word on the tape is the output.
- It is also possible to stop unsuccessfully or to run infinitely long.

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- This class is called co-NP.
- Example: SAT is in NP, while TAUT (checking whether a Boolean formula is a tautology) is in co-NP.

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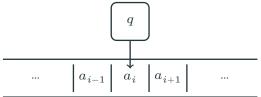
- Turing machines form a complete computational model, by the following Church – Turing thesis: any computation on a reasonable computing device can be performed on a Turing machine.
- Moreover, if the computation is polynomial, it can be performed also polynomially on the Turing machine.
  - The degree of the polynomial could change.

#### Theorem

SAT is NP-complete, that is, if  $A \in NP$ , then A is m-reducible to SAT.

Proof sketch.

- Suppose  $A \in NP$ , let us show  $A \leq_m^P SAT$ .
- We encode each configuration of the non-deterministic Turing machine for *A* as a binary word:



$$0^m \ a_1 \ \dots \ 0^m \ a_{i-1} \ q \ a_i \ 0^m \ a_{i+1} \ \dots$$

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- Next, we construct a formula  $\varphi_x$  with variables  $b_{00}, b_{01}, \dots$  which expresses the fact that this matrix represents a correct protocol of a successful execution.

- $\varphi_x$  is a conjunction of the following claims:
  - the first row represents the configuration with x on the tape, the machine observing its first letter;
  - each next row is obtained from the previous one by one of the rules of the machine;
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This is all expressible as Boolean formulae.

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- On the other hand, SAT is in NP, so it is NP-complete.

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- 3-SAT is a special version of SAT, where only 3-CNFs are allowed.
- Trivially, 3-SAT  $\leq_m^P$  SAT... but we need the opposite reduction!
- Let us show that SAT  $\leq_m^P$  3-SAT.

# Tseitin's Transformations

#### Theorem

For any Boolean formula *A*, there exists an equisatisfiable 3-CNF *B* of polynomial size.

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- Equisatisfiability means that *B* is satisfiable iff so is *A*.
- Constructing an *equivalent* 3-CNF of polynomial size is not always possible: even translation to CNF can lead to exponential blowup.

- Tseitin's transformations look like translation into 3-address (Assembler-like) code:
  - (a + b) \* (c + d) is translated to "add  $a \ b \ t_1$ ; add  $c \ d \ t_2$ ; mul  $t_1 \ t_2 \ r$ "

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• For each subformula we introduce a new variable and write the corresponding equivalences.

Example:  $(p \to q) \lor (q \to (p \to r))$ 

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 $\begin{array}{l} (t_1 \leftrightarrow (p \rightarrow q)) \land \\ (t_2 \leftrightarrow (p \rightarrow r)) \land \\ (t_3 \leftrightarrow (q \rightarrow t_2)) \land \\ (t_4 \leftrightarrow (t_1 \lor t_3)) \land \\ t_4 \end{array}$ 

#### Transform into 3-CNF by the following table:

$$\begin{array}{l} t_k \leftrightarrow (t_i \wedge t_j) \\ t_k \leftrightarrow (t_i \vee t_j) \\ t_k \leftrightarrow (t_i \to t_j) \\ t_k \leftrightarrow (t_i \to t_j) \end{array} \left| \begin{array}{l} (\neg t_i \vee \neg t_j \vee t_k) \wedge (t_i \vee \neg t_k) \wedge (t_j \vee \neg t_k) \\ (t_i \vee t_j \vee \neg t_k) \wedge (\neg t_i \vee t_k) \wedge (\neg t_j \vee t_k) \\ (\neg t_i \vee t_j \vee \neg t_k) \wedge (t_i \vee t_k) \wedge (\neg t_j \vee t_k) \\ (t_i \vee t_k) \wedge (\neg t_i \vee \neg t_k) \end{array} \right|$$

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For our example, we get:  $(\neg p \lor q \lor \neg t_1) \land (p \lor t_1) \land (\neg q \lor t_1) \land$   $(\neg p \lor r \lor \neg t_2) \land (p \lor t_2) \land (\neg r \lor t_2) \land$   $(\neg q \lor t_2 \lor \neg t_3) \land (q \lor t_3) \land (\neg t_2 \lor t_3) \land$   $(t_1 \lor t_3 \lor \neg t_4) \land (\neg t_1 \lor t_4) \land (\neg t_3 \lor t_4) \land t_4$ 

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#### Theorem

3-SAT  $\leq_m^P$  INDSET, therefore, INDSET is NP-complete.

Reduction: given a 3-CNF φ, construct a graph G and give a number k (i.e.,
 (G, k) = f(φ)), such that G has an independent set of k vertices iff φ is satisfiable.

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  (G, k) = f(φ)), such that G has an independent set of k vertices iff φ is satisfiable.
- Satisfiability is equivalent to taking, from each clause, one literal, so that the resulting set of literals is non-contradictory.

• Example:

 $(z \vee \bar{w} \vee \bar{y}) \wedge (y \vee \bar{x} \vee \bar{w}) \wedge (x \vee w) \wedge (\bar{y} \vee \bar{x} \vee \bar{z})$ 

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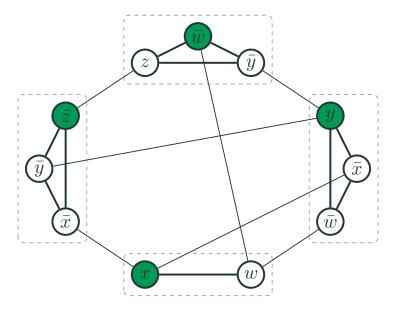
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- We shall construct a graph in which each 3-clause will be modelled by a triangle (and each 2-clause by an edge, and each 1-clause by a vertex), and connect contradicting literals.
- *k* will be the number of clauses. Thus, we are forced to take exactly one vertex from each clause.



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- Search problem: yield a witness or say "no."
- **Counting problem** (the #P class): yield the number of witnesses.

- An NP decision problem is the question whether there exists a witness y such that R(x, y) = 1.
  - E.g., a satisfying assignment for  $\varphi$ .
- Search problem: yield a witness or say "no."
- **Counting problem** (the #P class): yield the number of witnesses.
- Finally, we could ask for **all** witnesses.

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  - This gives a poly-time algorithm for the search problem for 2-CNF.
- The counting problem could be harder than the decision one (example: DNF-SAT).